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An improved sliding window: long short-term memory modeling method for real-world capacity estimation of lithium-ion batteries considering strong random charging characteristics.

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1	An improved sliding window - long short-term memory modeling method for real-world
2	capacity estimation of lithium-ion batteries considering strong random charging characteristics
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6	Denmark; ⁴ School of Pharmacy and Life Sciences, Robert Gordon University, Aberdeen AB10-7GJ, UK.
7	Abstract: Capacity estimation plays a significant role in ensuring safe and acceptable energy delivery, especially under
8	real-time complex working conditions for whole-life-cycle lithium-ion batteries. For high-precision and robust capacity
9	estimation, an improved sliding window-long short-term memory (SW-LSTM) modeling method is proposed by introducing
10	multiple time-scale charging characteristic factors. The optimized feature information set is extracted by constructing an
11	optimized differential integration-moving average autoregressive (DI-MAA) model, which is introduced as the input matrices
12	of the whole-life-cycle capacity estimation model. With the constructed DI-MAA model, the relevant features are effectively
13	extracted, overcoming the data limitation problem of the long-term dependence capacity estimation. For the experimental
14	test, the maximum capacity estimation error is 3.56%, and the average relative error is 0.032 under the complex Beijing bus
15	dynamic stress test working condition. The proposed SW-LSTM estimation model with optimized DI-MAA-based data pre-
16	processing treatment has high stability and robust advantages, serving an effective safety assurance for lithium-ion batteries
17	with real-world complex working condition adaptation advantages.
18	Keywords: lithium-ion battery; sliding window - long short-term memory; capacity estimation; differential integration -
19	moving average autoregressive model; multiple time-scale factors
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21	Highlights:
22	• An improved SW-LSTM model is constructed for real-time capacity estimation

- The optimized DI-MAA strategy is formed for feature extraction and data pre-processing
- The high-accuracy results are obtained with the real-world capacity estimation error of 3.56%
- The proposed model has high stability and accuracy for real-world capacity estimation
- 26 1. Introduction

With the advantages of fast charging ability, high energy density, low self-discharge rate, no memory effect, and a long lifespan, lithium-ion batteries are widely used in new energy vehicles (EVs), communication facilities, electrical equipment in aeronautics, smart devices such as mobile phones, laptops, grids, etc. [1, 2]. However, the battery's capacity performance decreases inevitably along with an increasing number of charge-discharge cycles, which results in capacity and power fade in addition to electrochemical instabilities causing thermal runaways and fire accidents. Consequently, accurate capacity estimation by the battery management systems (BMS) is not only crucial for the safety assurance of lithium-ion batteries but also plays a significant role in the real-time application of EVs [3-5].

34 Most of the capacity estimation methods are limited by the length of the training data, which cannot adapt to robust realworld applications. Also, their value is difficult to estimate accurately when the testing and training datasets are different 35 under various working conditions [6-8]. Many battery-based industrial applications suffer from a lack of maintenance, 36 37 adverse working conditions, and poor operation, which leads to an accelerated battery degradation process. It is the reason 38 why online capacity estimation is becoming a hot research topic [9-12]. Using the dynamic impedance changes can realize 39 the capacity estimation purpose, including the model-based and data-driven methods. The data-driven methods do not need 40 to establish a specific battery model based on the complex electrochemical and degradation mechanisms [13-17]. Only the 41 monitoring data is used in the cyclic charge-discharge processes to fit the degradation law of battery performance, which is more universal than the model-based methods. To realize reliable energy and safety management, high-precision capacity 42 43 estimation plays an important role in the BMS along with the battery system application.

Along with the development of cloud computing, data-driven methods are becoming increasingly attractive for online capacity estimation. However, existing data-driven methods still have low accuracy and weak robustness [18]. Due to the

46 characteristics of capacity regeneration, nonlinearity, and random fluctuation of lithium-ion batteries, the generalization 47 ability is poor when only a single-scale feature is used to realize the capacity estimation. Consequently, the convolutional 48 neural network (CNN) is introduced into the degradation model as an effective deep learning (DL) method. It realizes capacity 49 estimation using sparse data segmentation through cloud computing and extracts hidden feature information of different 50 depths effectively [19-21]. The hybrid validation dataset-based induced order weight geometric averaging operator is also constructed to precisely capture the extracted features, which are related to the health status and remaining useful life (RUL) 51 52 of lithium-ion batteries based on a variant long short-term memory (LSTM) neural network [22]. The data-driven support 53 vector machine (SVM), LSTM network, and Gaussian process regression are introduced to realize the capacity estimation 54 with the support of the extracted health features. The spatiotemporal relationships are extracted using the random forest algorithm to capture nonlinear characteristics for multi-step-ahead capacity estimation [22-27]. The hybrid model based on 55 56 an attention mechanism and bidirectional (Bi) LSTM model is established for the RUL prediction using whole-life-cycle 57 datasets [28], constructing new hidden layer discarding techniques. This modeling strategy prevents the model overfitting 58 phenomenon and enables accurate RUL prediction based on capacity traction combined with soft perception, accommodating 59 local regeneration and fluctuations [29-31]. The deep domain adversarial networks are constructed with an unsupervised 60 feature alignment metric by considering the maximum mean discrepancy and correlation alignment [32]. However, due to insufficient data pre-processing, the model is disturbed by the noise component of the original input data [33, 34]. With the 61 62 continuous enhancement of artificial intelligence algorithms, the deep learning theory has been gradually popularized and applied, especially the LSTM-based model construction concept, which has become a significant methodology for the 63 64 capacity estimation of lithium-ion batteries.

Due to the enhanced capabilities of the LSTM network and other modeling methods, they have been constructed to improve the accuracy of capacity estimation for lithium-ion batteries [35-37]. The LSTM network performs well at time series estimation, which is used to establish a capacity estimation framework. A controllable deep transfer learning (CDTL) model is constructed for the short- and long-term charge state estimations at early stages of degradation based on improved

69	LSTM architectures, making it have better generalization ability in the estimation process under different stress conditions
70	[38]. A hybrid approach for online cycle lifetime estimation has been proposed by combining a Bi-LSTM model with the
71	attention mechanism (Bi-LSTM-AM) in comparison to a support vector regression (SVR) model [39]. The proposed method
72	is based on the initial temperature data measured online, which is updated using the SVR model to obtain advanced multi-
73	step temperature estimation. Then, the Bi-LSTM-AM model is constructed to predict the cycle life status. Parallel attention
74	networks are constructed by combining multivariate time series to extract the relationship between the selected health features
75	and the state of health (SOH) factor [40, 41]. Finally, a novel parallel learning framework is constructed by integrating an
76	attention mechanism and the LSTM network, which can fully utilize the health features and help to solve the challenging
77	issues of estimation accuracy and robustness [42]. Combining the characteristics using an adaptive gated recurrent unit (GRU),
78	a DL-based RUL prediction network is constructed to describe the uncertainty of estimation results through a Monte Carlo
79	optimization. An integrated capacity estimation method is proposed by conducting the local tangent space alignment (LTSA)
80	feature extraction and adaptive sliding window (ASW)-LSTM model [43]. The indirect health indicator (HI) is extracted
81	automatically by the LTSA to replace the immeasurable capacity. Then, its strong correlation is verified by the Spearman
82	correlation coefficient. For high-precision capacity estimation, multiple optimization strategies are proposed with the LSTM-
83	based main modeling structure that is suitable for whole-life-cycle capacity estimation.
84	To improve model accuracy, an improved LSTM-RNN model is employed to express the long-term dependencies among
85	the degraded capacities of lithium-ion batteries. Consequently, the procedure is optimized adaptively using the resilient mean
86	square backpropagation calculation and the dropout technique [44]. DL-based prognostic methods are introduced with online
87	validation, according to which the effective variety of RNNs with the LSTM architecture is constructed with variable input
88	dimensions that facilitate the network training process with additional labeled samples [45-47]. An attention-based RNN
89	model is constructed to improve the prognostics and health management effect, which enables a more accurate estimation of
90	output voltage degradation using the original long-term dynamic cycle durability test data [48]. In contrast, the DL-based
91	method is easy to operate, overcoming the whole-life cycle capacity estimation problem effectively [49-52]. Higher inter-

92 cycle aging resolutions are realized for faster and more accurate estimation by considering the temporal patterns and cross93 data correlations in the raw data of terminal voltage, current, and cell temperature [53-58]. Considering the whole-life-cycle
94 characteristics of battery-based energy supply conditions, lots of inner and outer factors should be considered in the iterative
95 calculation processes.

96 In the present DL-based capacity estimation methods, the whole-life-cycle information effect on multiple inner-state 97 factors is not considered comprehensively. Therefore, by considering the internal parameter coupling mechanism of capacity, 98 impedance, and temperature, this paper presents an improved sliding window-long short-term memory (SW-LSTM) model 99 for accurate cycle-to-cycle capacity estimation, which is adaptive to complex working conditions for lithium-ion batteries. 100 In the proposed SW-LSTM-based iterative calculation and capacity estimation process, an optimized differential integration - moving average autoregressive (DI-MAA) modeling strategy is introduced for feature extension to realize the feature 101 102 information optimization and optimize the historical data together with the estimation models of formulations, improving the 103 estimation accuracy even despite short-term test data containing insufficient global degradation information. The optimized 104 iterative calculation strategy is introduced into the capacity estimation process and characterizes the degradation patterns 105 simultaneously through uncertainty estimation and variational inference, improving the capacity estimation effect and fault 106 diagnosis performance for high-efficiency predictive maintenance.

107 The remaining sections of this article are organized as follows: Section 2 is the mathematical analysis, in which the 108 proposed improved SW-LSTM model and the established DI-MAA modeling strategy for feature extraction and optimization 109 are described. Section 3 presents the experimental battery tests, the capacity estimation, and the validation results. Finally, 110 the conclusion and future research plans are presented in Section 4.

111 2. Mathematical analysis

112 2.1. Upgraded sliding window - long short-term memory modeling framework

113 The improved SW-LSTM model is constructed, the framework of which involves three main stages for achieving the

114 capacity estimation objectives. (1) The charging capacity is selected as the health factor innovatively, reflecting the

5

115 degradation trend for the cycle-to-cycle capacity estimation. In the real-world application process, it is easier to measure the 116 charging capacity with the constant current-constant voltage (CC-CV) charging process than with the complex varying 117 current in the discharging process. Also, to make the result more accurate, the fluctuation caused by the capacity recovery 118 phenomenon in the original data is removed by using the adaptive sliding window method with smoothing techniques. Then, 119 the capacity series is obtained from a relatively stable degradation trend. (2) Using the smoothed capacity sequence, the 120 residual and finite modal components are extracted to reflect the main degradation trend. (3) The residuals are extracted to 121 form the training dataset, which is combined with the LSTM network to establish the mapping relationship between early and late capacities to estimate the unknown capacity series. According to this designed framework, the cycle-to-cycle capacity 122 123 is estimated during the iterative calculation process after the starting point is determined. 124 The features of the real-world parameters are considered to express the aging characteristics, mainly including current 125 magnification, SOC, temperature, and other parameters. Then, the processing model is constructed accordingly to reflect the 126 influence of the operating conditions effectively, realizing the weight coefficient preset effectively. Considering the 127 instantaneous voltage drop and the degradation processes that occur when the load current is formed, the variation law is 128 explored to obtain the influencing factors of internal ohmic resistance and polarization effects. Then, it is combined with the 129 phased expression of instantaneous voltage rise, deceleration, and stabilization after the current interruption. With the concept 130 of pre-processing treatment for state evaluation, the iterative calculation and correction procedure of the SW-LSTM model

is constructed for the cycle-to-cycle capacity estimation, as shown in Figure 1.



132

133

Figure 1. Capacity correction and estimation based on the SW-LSTM model

134 In Figure 1, the original input data are normalized firstly. Then, the optimized feature subset performance evaluation is extracted as the input of the LSTM model by introducing the sliding window smoothing strategy. When all functional subsets 135 136 are evaluated by levels, the best output is obtained. Exceptionally, the cell-to-cell LSTM estimation model is an improved 137 version of the recurrent neural network (RNN), which is introduced to eliminate the gradient vanishing and explosion problems during the backpropagation through time to retain the ability of the network to solve long sequence dependence 138 139 prediction [59, 60]. The key element of LSTM is the memory cell, which is at the center of each linearly activated neuron. It 140 can be thought of as a channel for the addition of new information or the removal of some information. Using "gates" and other structures in this process, the flow of information is successfully handled [61]. 141

The status of the memory cell is saved and controlled through three determined gates, including the forget gate, the input gate, and the output gate, which are expressed by f_t , i_t , and o_t , respectively. The forget gate is used to decide what information should be discarded from the cell state in the capacity estimation process, as shown in Equation (1).

$$f_t = \sigma \Big(W_{fh} \Box_{t-1} + W_{fx} x_t + b_f \Big) \tag{1}$$

In Equation (1), f_t is the output of the forget gate; σ is the sigmoid function; W_{fh} and W_{fx} are the weight matrices of the forget gate used for the training of the network. \Box_{t-1} is the median hidden state of the output gate for the present LSTM unit; x_t is the input of the neuron at time point t and b_f is the bias vector of the network. Similarly, the input gate is constructed to output the computational calculation result of the sigmoid and the hyperbolic tangent functions to the next layer. The mathematical calculation processes of the input gate and the memory cell are shown in Equation (2).

$$\begin{cases} i_t = \sigma(W_{ih} \square_{t-1} + W_{ix}x_t + b_i) \\ \tilde{C}_t = tanh(W_{ch} \square_{t-1} + W_{cx}x_t + b_c) \end{cases}$$

$$\tag{2}$$

In Equation (2), i_t is the input gate; σ is the sigmoid function; W_{ih} and W_{ix} are the weight matrices attached to the input gate during the training of the network; \Box_{t-1} is the median hidden state of the present LSTM unit. b_i and b_c are the bias vectors for the input gate and cell memory, respectively; \tilde{C}_t is the call state at the present time point; tanh is the hyperbolic tangent function; W_{ch} and W_{cx} are the weight matrices attached to the memory cell during the update of the current relevant information that needs to be stored in it. Finally, the output layer is constructed to update the old cell state to the new cell state, as shown in Equation (3).

$$\begin{cases} C_t = f_t C_{t-1} + i_t \tilde{C}_t \\ o_t = \sigma(W_o \Box_{t-1} + W_o x_t + b_o) \\ \Box_t = o_t \cdot tanh(C_t) \end{cases}$$
(3)

In Equation (3), C_t is the cell state information at the present time point; f_t is the forget gate and the functional relationship (•) is the Hadamard point-by-point multi-application component. C_{t-1} is the memory state at the last time point. i_t is the input gate. \tilde{C}_t is the cell state factor of the neuron state at the present point and o_t is the information of the output gate. W_o is the weighting matrix for the output gate after the training process. \Box_{t-1} is the output of the hidden layer for the previous time point t - 1. b_o is the bias vector of the output gate. \Box_t is the output of the hidden layer for the previous time point t.

162 In the proposed SW-LSTM model, the learning ability of the long-order dataset treatment is greatly improved with front 163 and back dependencies by considering the learning effects, which include past and future states on the current capacity state parameters simultaneously. With this treatment, the disadvantages in the training and testing processes, including only studying the impact of past state factors on current state factors, are effectively overcome for the LSTM network, by ignoring the role of future states. Also, the inefficient use of the pre-dependence and post-dependence of time series is retarded, as it is the limited ability of data learning. The improved SW-LSTM network can benefit from the time-series data independently through the recurring process in the step-by-step gating layers. The feed-forward processing results from the input and forget layers are introduced into the output layer simultaneously, which can make full use of the life information contained in the past and future time data sequences.

In the form of cyclic iteration for the pre-treatment to the evaluation and prediction steps, the model parameters, state variables, and variance are modified in real-time to improve the accuracy of the capacity estimation, which is used to enhance the model's adaptability under complex working conditions. When the noise is unknown, the internal resistance is estimated by controlling the error range to improve stability and convergence in the capacity estimation process. The LSTM-RNNbased estimation network is constructed for feature optimization, as shown in Figure 2.



176



Figure 2. Construction of the LSTM-RNN-based estimation network for feature optimization



183 to deeply explore the implicit relationship between aging inducement, multi-parameter estimation, and cycle life during the 184 capacity estimation process. Over time, the data scale and quality available for the network's training set are supposed to 185 increase gradually by flowing through the constructed LSTM-RNN framework, which improves the capacity estimation 186 accuracy synchronously. To solve the RNN-based gradient explosion or disappearance problems, the LSTM-based network 187 is introduced into the calculation procedure, in which the state unit of the RNN is replaced by the cyclic unit structure of the 188 LSTM network. When constructing the LSTM-RNN-based estimation model, the structural bi-directional design is considered for the input, output, and hidden layers, as well as the training and estimation of the network, including the forward 189 190 direction and backward direction computation processes, as shown in Figure 3.







Figure 3. An illustrative framework of the power battery for time series estimation based on LSTM-RNN

193 In Figure 3, each gate in the network has a weight W_f , W_i , W_c , and W_o associated with the forget gate, input gate, 194 memory cell, and output gate, respectively. Also, the network possesses a bias b_f , b_i , b_c , and b_o vector attached to each 195 gate. This pre-treatment is conducted to enhance the network flexibility and make it adaptive to the training data for accurate 196 battery characterization by filtering out the observation noise and process noise, which are affected by environmental 197 conditions and restricted by the computing power of BMS processors. The main structure of the optimized bidirectional SW-198 LSTM model is constructed by the combination of two unidirectional recurrent networks, in which the inputs are the same, 199 and the information is transmitted in opposite directions with symmetrical structures. Correspondingly, the multiple LSTM components are introduced to extract the bidirectional spatiotemporal feature information, as shown in Equation (4). 200

$$\begin{cases} h'_{t} = f(W_{1}x_{t} + W_{3}h'_{t-1} + b'_{t}) \\ h_{t} = f(W_{2}x_{t} + W_{4}h_{t-1} + b_{t}) \\ H_{t} = h'_{t} \bigoplus h_{t} \end{cases}$$
(4)

In Equation (4), h'_t is the hidden layer state output, h_t is the hidden layer state information, f is the activation function of the hidden layer, and \oplus is the vector concatenation operator.

To eliminate the influence of the measurement unit and its magnitude in the input data for the vector of current, voltage, and temperature, it is normalized to improve the robustness, convergence rate, and acceleration of the gradient descent for the LSTM network. Specifically, before the input data are introduced into the LSTM network for real-time capacity estimation and iterative calculation, [-1, 1] is used to normalize the index data, including voltage, current, temperature, and SOC, as shown in Equation (5).

$$x_{nom} = \frac{2(x - x_{min})}{x_{max} - x_{min}} - 1$$
(5)

208 In Equation (5), x_{nom} is the normalized data and x is the original data for the input vector of current, voltage and 209 temperature. x_{max} is the maximum value in the original data. x_{min} is the minimum value in the original data. 210 In the early estimation stage, a multivariate hidden Markov model (HMM) is constructed to conduct a multi-factor real-211 time weighted correlation of aging incentives, state parameters, and rated capacity to achieve accurate short-term SOC 212 estimation and error correction, which is also used as one input parameter for the real-time capacity estimation. In the latter 213 estimation process, combined with the LSTM-RNN network framework, the improved dual feedback correction mechanism 214 of features and time series is introduced to conduct the capacity estimation considering both the long-term and short-term 215 memory time series. The correlation and time dependence are used to improve the estimation accuracy. The correlation 216 relationship is extracted between characteristic parameters, environmental conditions, and operation data. After that, the real-217 time correction of auxiliary information is realized by independently optimizing key time points and enhancing mathematical 218 expressions, which is used to improve the estimation effect and stability over a long period. 219 2.2. Differential integration - moving average autoregressive modeling method

220 The LSTM component only considers the influence of past states on current states by ignoring the role of future state

221	parameters, so it does not consider the pre- and post-dependent time series problem and has a limited ability to learn the data
222	information. The proposed SW-LSTM model learns the effects of past and future states on the current state simultaneously,
223	which greatly improves the learning ability of the model for long-order data with front and rear dependencies. The DI-MAA
224	model is constructed to process the time series data independently through the forward and backward layers, which feed the
225	processing results of the two layers to the output layer. Consequently, it can make full use of the life information contained
226	in the past and future time sequence data. By constructing the deep neural network with a recursive architecture, the higher-
227	level data features are extracted from the original data. With the existence of the gate structure, the DI-MAA model can judge
228	and screen the past information flow itself. Then, the full learning of the training set is completed. Finally, the nonlinear
229	mapping relationship between the early and later stages of capacity is established. The unreasonable interval in the original
230	capacity series is eliminated. The program operation has little correlation with the amount of data, so the execution time is
231	constant.
232	With the DI-MAA pre-processing of the measured datasets, the SW-LSTM-based capacity estimation model has a strong
233	learning ability for time series data and can achieve higher accuracy. The result of the model is interval estimation rather than
234	point-to-point, which reflects the uncertainty. After the DI-MAA-based data treatment, the SW-LSTM model is introduced
235	into the model to describe the uncertainty of the estimation results. The parameters of the SW-LSTM model are regarded as
236	random variables subject to a certain distribution, in which X represents the training dataset and Y represents the
237	corresponding real capacity value. As for the nonlinear characteristics of the lithium-ion batteries, the sliding time window
238	is constructed to extract the new feature of the measured dataset, which is then introduced into the SW-LSTM model as an
239	input, and the DI-MAA-based pre-processing architecture is designed, as shown in Figure 4.





Figure 4. The DI-MAA-based new dataset construction process for the input pre-processing of the SW-LSTM model

242 In Figure 4, the dataset is pre-processed using the DI-MAA-based pre-processing architecture as well as the fixed sliding window with a window length of K - 1. The first data sequence from X(t - K) to X(t - 1) in the processing window is 243 244 used as the input of the SW-LSTM model. The last data vector is taken as the corresponding output. Using the sliding window, 245 multiple sets of features are extracted for the input and output data sequences. It reduces the role of irrelevant parts by 246 designing various weighting coefficients for different calculation parts. This " many-to-one" structure can improve the utilization ability of the estimation model for the historical discharge data. Even if the discharge data at different historical 247 times in the input sample have different effects on the current state parameters, they are equally treated using this modeling 248 249 structure effectively. Therefore, to improve the filtering effect of the window data as model input, an effective attention 250 mechanism is designed to make the model give priority to the discharge data that has a great impact on the current state 251 parameters. Consequently, it further improves capacity estimation accuracy, which is adaptive to complex working conditions. 252 The steps of the attention mechanism are designed accordingly.

Firstly, a scoring function is used to calculate the correlation score of the eigenvector between $h_{t,i}$ and h_t for the discharge data at each time in the hidden state. This step is realized by a full connection layer with the number of output nodes τ , and its input is the hidden state h_t^T after transposition, as shown in Equation (6).

$$score([h_{t,i}, h_t]) = W_s h_t^T + b_s$$
(6)

In Equation (6), W_s is the weight matrix and b_s is the bias vector of the full connection layer. $score([h_{t,i}, h_t])$ is the

relevant information between $h_{t,i}$ and h_t . Then, the attention weight α_i of each time input data in the sample is obtained by using the softmax function. Its weighted aggregation with $h_{t,i}$ is used to obtain the output h_t^* of the attention layer, as shown in Equation (7).

$$\begin{cases} \alpha_{i} = \frac{exp\{score([,h_{t}])\}}{\sum_{j=1}^{\tau} exp\{score([h_{t,i},h_{t}])\}} \\ h_{t}^{*} = \sum_{j=1}^{\tau} \alpha_{i}h_{t,i} \end{cases}$$
(7)

Finally, h_t^* is input into the full connection layer with one output node, obtaining the estimation value of the state factor, as shown in Equation (8).

$$\hat{y}_t = W h_t^* + b \tag{8}$$

In Equation (8), *W* is the weight matrix of the full connection layer, and *b* is the bias vector. The random variable $\theta = \{W, b\}$ is constructed to represent the model parameters. Considering the complexity of calculating the key divergence when there are many neurons, the objective function is optimized under the L2 regularization condition using the equivalence between the dropout layer and Bayesian variational inference, as shown in Equation (9).

$$L_{dropout} = \frac{1}{p} \sum_{t \in S} E(Y, \hat{Y}) + \sum_{h=1}^{H} [\lambda ||W||^2 + \lambda ||b||^2]$$
(9)

In Equation (9), *S* is the subset of training samples and *p* is the number of subsets. *H* is the total number of model parameters, \hat{Y} is the model output obtained by dropout, and λ is the attenuation coefficient of regularization. This objective function is optimized using the adaptive moment estimate (ADAM) optimizer. When the optimal approximate distribution of the posterior distribution of the model parameters is obtained, the distribution of the model capacity estimation results for the newly obtained input sample X^* is extracted, as shown in Equation (10).

$$p(Y_t^*|X_t^*, X, Y) = \int p(Y_k^*|X_k^*, \theta) q^*(\theta) \, d\theta = \frac{1}{T} \sum_{t=1}^T p(Y^*|X^*, \hat{\theta}_t)$$
(10)

271 In Equation (10), $\hat{\theta}_t$ is the specific sampling value of $q^*(\theta)$, and T is the cyclic sampling number.

272 2.3. Uncertainty quantification and evaluation criteria

To evaluate the capacity estimation effect of the proposed SW-LSTM model, the mean absolute error (MAE), root mean square error (RMSE), mean absolute percentage error (MAPE), and R^2 (coefficient of determination) metrics are introduced

275 for critical analysis in real-world applications, as shown in Equation (11).

$$E_{t} = y_{t} - \hat{y}_{t}$$

$$MAE = \frac{1}{m} \sum_{t=1}^{m} |y_{t} - \hat{y}_{t}|$$

$$RMSE = \sqrt{\frac{1}{m} \sum_{t=1}^{m} (y_{t} - \hat{y}_{t})^{2}}$$

$$MAPE = \frac{1}{m} \sum_{i=1}^{m} \left| \frac{y_{t} - \hat{y}_{t}}{y_{t}} \right|$$

$$R^{2} = 1 - \frac{\sum_{t=1}^{N} (E_{t})^{2}}{\sum_{t=1}^{N} (y_{t} - \bar{y})^{2}}$$
(11)

In Equation (11), m is the total number of data points. y_t represents the real capacity value of the lithium-ion batteries at the *t*th time point. \hat{y}_t represents the estimated capacity value and \bar{y} is the average value of the actual SOC of the model at the *t*th time point. 3. Experimental Section

280 3.1. *Experimental platform design*

The instruments include charge-discharge battery test equipment, a temperature chamber, and other supporting experimental equipment, providing a suitable and safe battery test environment. The experimental battery test platform is designed, as shown in Figure 5.



284



Figure 5. Experimental test platform for complex current-temperature working condition tests

286 In Figure 5, the experimental test procedure is designed and embedded in the host computer that is connected to the CT-4016-5V100A-NTFA charge-discharge battery tester using a TCP/IP channel. According to the platform design, the signals 287 288 of U/I/T are measured accurately online. All the testing batteries are fixed in the chamber, according to which the time-289 varying current, voltage, and temperature variables under the test working conditions are constructed. As the model 290 parameters vary along with the changing temperature, trials are conducted at an ambient temperature of 25 °C. Meanwhile, 291 the reference performance test is conducted at 0, 25, and 45 °C temperature conditions with a current rate of 0.3, 1, and 2 C. 292 Then, the varying-temperature model parameters are further improved and applied in the iterative calculation process 293 according to the complex working condition requirements.

294 3.2. Capacity estimation effect and analysis

295 The whole-life-cycle experimental test is conducted for the capacity estimation and verification effect of the proposed 296 SW-LSTM model. The shared link of the original dataset is <u>https://www.researchgate.net/project/Battery-life-test</u>. It is the 297 whole-life-cycle experimental data carried out by the research team members in the early stages. It is completed in cooperation for the whole year, even including the early-stage experimental design process and Origin graphing software. In 298 16 this verification, the battery cell numbered 007 is selected, and the charging capacity recording dataset is introduced into the training and testing processes.

As for the whole-life-cycle variation in adaptive ability, the 20*25 = 500 cycling Beijing bus dynamic stress test (BBDST) experimental data are considered. During the application process, the discharging process is determined by the realistic application requirements, and only the parameters of the charging process are recorded. The charging capacity is used for the main variation analysis to make the proposed SW-LSTM model suitable for real-time application. The charging capacity is not only influenced by the aging process, but also influenced by working conditions and the environment, so it has a large and complex change, which will make the capacity estimation difficult, as shown in Figure 6.





(b) Charging capacity estimation with W5_T300P200



(c) Charging capacity estimation with W10_T300P200

(d) Charging capacity estimation with W20_T300P200

307 Figure 6. Charging capacity variation and estimation curves with varying window length comparison under the real-world BBDST working conditions

308 In Figure 6, Wm is the window width of m, including 5, 10, and 20, and $T_x P_y$ is the origination with a training dataset 309 length of x = 300 and an estimation dataset of y = 200. Also, F and P denote filtering and predicting, respectively. For 310 filtering, the dataset is directly used when measured by the sensors. For prediction, the capacity is estimated using the existing 311 dataset from the previous time points after training the network. The blue and green curves represent the cycle-to-cycle 312 capacity estimated by the SW-LSTM model, respectively. Compared with other window width values, these values have a 313 better estimation effect. For the comparison of subfigures (b), (c), and (d), the W10 has an optimal estimation effect with 314 an overall best RMSE value of 3.2453%, an MAE value of 1.7065%, a MAPE value of 1.0189%, and an R-squared value of 315 92.722% showing high adaptability and robustness in accurately estimating the capacity of lithium-ion batteries using this 316 parameter value. Meanwhile, using a sliding window size of 20, it can be observed that the capacity estimate loses track of the actual capacity with high levels of fluctuation near the end of discharge. Using the RMSE, MAE, MAPE, and R-squared 317 318 metric values for the charging capacity estimation by the proposed SW-LSTM model is shown in Figure 7.









(b) MAE histogram

(c) MAPE histogram

(d) R-squared histogram

Figure 7. Evaluation metric curves for different capacity estimations using different sliding window sizes

319	In Figure 7, compared with the estimation result using different sliding window sizes, it can be observed that the metric
320	values of W10 are relatively optimal, and the charging condition capacity estimation of the battery is consistent. Its RMSE,
321	MAE, MAPE, and R-squared values are 3.2453%, 1.7065%, 1.0189%, and 92.722%, respectively. The results of the proposed
322	SW-LSTM estimation model show a high level of robustness, especially for these metrics when using different sliding
323	window sizes at the same training and testing cycles.
324	3.3. Varying training-estimation length adaptive analysis
325	The charging capacity is affected by various uncertain factors in the working process, so the collected data contains a lot
326	of noise and fluctuation. If the original data is directly used for modeling without pre-processing, the model's accuracy is
327	highly reduced. The necessary data pre-processing improves the accuracy of the estimation model. Through the adaptive data
328	pre-processing method proposed in this paper, the original capacity data is smoothed and denoised, so the processed data has
329	a steady trend of monotonic decline. The proposed SW-LSTM model is constructed to learn the degradation trend in early
330	life to establish the estimation model, which is then introduced into the capacity estimation process to obtain accurate results.
331	The estimation effects of the SW-LSTM and LSTM models are conducted and analyzed under different operating conditions
332	to test the adaptive ability of the varying training and testing lengths. By conducting different starting time tests for the effect
333	verification using different sliding window sizes, it is observed that the estimation model has the same adaptive ability except
334	for sliding window size 10, which showed optimal results. Upon selecting a W10 as the optimal sliding window value, the
335	degradation trend for the real-world dataset with good evaluation effects at different training and prediction cycles is shown
336	in Figure 8.





(a) Charging capacity estimation with W10_T200P300

(b) Charging capacity estimation with W10_T300P200



(c) Charging capacity estimation with W10_T250P250



337 Figure 8. Charging capacity estimation adaptive to varying training-testing datasets under the real-world BBDST working condition 338 In Figure, different conditions for the training and testing datasets are designed and realized with high accuracy. The blue 339 and green lines represent the cycle-to-cycle capacity estimated by the SW-LSTM model. The estimation results are obtained 340 for four types of datasets with four starting cycle-number points. It can be observed that when the battery's capacity is 341 estimated by the proposed SW-LSTM model, the result fluctuates around the actual capacity curve, and there is only a slight 342 difference between the two curves is slightly different under the two conditions. The estimation result has the same changing 343 trend compared with the filtered capacity variation when using a window width of 10. To verify the estimation effect of the SW-LSTM model adapting to different starting points, the W10_T300P200, W10_T300P200, W10_T250P250, and 344

W5_T350P150 experiments are conducted. For different conditions, the predicted effect has a good estimation effect and a
similar degradation trend to the original capacity fading trend. The results show that the estimation effect has an overall best
RMSE value of 3.2453%, an MAE value of 1.7065%, a MAPE value of 1.018%, and an R-squared value of 92.72%. These
estimation results demonstrate how adaptable and accurate the SW-LSTM model is for estimating lithium-ion battery capacity.
The final comparative performance results using the RMSE, MAE, MAPE, and R-squared for the results presented in Figure
8 are shown in Figure 9.



Figure 9. Evaluation metric curves for different training and prediction cyclic capacity estimation



- 355 respectively, exhibiting high robustness for real-world capacity estimation of lithium-ion batteries.
- 356 3.4 Comparison of the proposed model with other existing methods
- 357 In this section, the estimation performance of the proposed model is compared with that of other machine learning methods,
- 358 such as deep transfer convolutional neural network (DTCNN), Fiber Bragg Grating-Gaussian Process Regression (FBG-
- 359 GPR), and sine cosine algorithm-salp swarm algorithm-extreme learning machine (SCA-SSA-ELM), using the MAE, RMSE,
- 360 MAPE, and R-squared to verify the model's superiority and demonstrate the indispensable contribution, as shown in Table
- 361 1.
- 362

Table 1. Comparison of the proposed SW-LSTM with other existing methods

Methods	MAE	RMSE	MAPE	R-squared
DTCNN [62]	-	2.20%	2.47%	-
FBG-GPR [63]	1.02%	0.62%	-	-
SCA-SSA-ELM [64]	0.538%	1.156%	0.887%	99.98%
HFCM-LSTM [65]	0.46%	0.91%	-	-
Proposed SW-LSTM	0.019656%	0.033242%	1.1833%	92.08%

It can be observed from Table 1 that the capacity estimated by the proposed SW-LSTM model is optimally compared to the other existing methods using the same metrics as the reference value, which indicates that the proposed SW-LSTM model has high levels of robustness and low error. The findings of the current study and a few pertinent, recently published research studies are summarized in Table 1, which makes it clear that the proposed SW-LSTM prediction model offers good prediction accuracy over an extended period. This also serves as further evidence that the SW-LSTM model has distinct advantages in estimating lithium-ion battery capacity and has a strong capacity for generalization in real-world conditions.

369 4. Conclusion

Efficient and accurate capacity estimation plays an important role in battery health management. To overcome the difficulties with accurate capacity estimation, the improved SW-LSTM model is constructed by considering multiple time scale factors, in which the convolutional calculation and data distribution model are optimized by constructing an optimal DI-MAA model, thus building a DL network with both speed and accuracy for high-precision capacity estimation only using

374	the high-randomness charging characteristics. The typical dynamic time is expanded statically to obtain the complete
375	characteristics of time and space as two-dimensional information, forming a strong adaptive estimation algorithm combined
376	with iterative optimization exploration. In the experimental verification process, the maximum capacity estimation error is
377	3.56%, and the average relative error is 0.032 under the complex real-world BBDST working conditions when only taking
378	the rich-noise charging dataset as input. It has high accuracy, reduces estimation error, and has good stability, which provides
379	a reference for the capacity estimation research of lithium-ion batteries. The proposed SW-LSTM estimation model deeply
380	analyzes the battery characteristics by revealing the modeling and optimization mechanisms with the DI-MAA dataset pre-
381	processing strategies. Consequently, a robust cycle life estimation model that is adaptive to complex working conditions has
382	been established, which lays the theoretical foundation for the industrial application and promotion of lithium-ion batteries.
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389	Author Contribution
390	Shunli Wang: Conceptualization, methodology, and software.
391	Paul Takyi-Aninakwa: Software and validation.
392	Siyu Jin: Visualization and investigation.
393	Ke Liu: Data curation, writing, and original draft preparation.
394	Carlos Fernandez: Writing-reviewing and editing.

395 Data Availability

396 All data included in this study are available upon request by contact with the corresponding author.

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